

1 **Electronic Supplemental Materials for “Blue whales respond to simulated mid-frequency**  
2 **sonar”**

3  
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9 **Author contributions:**

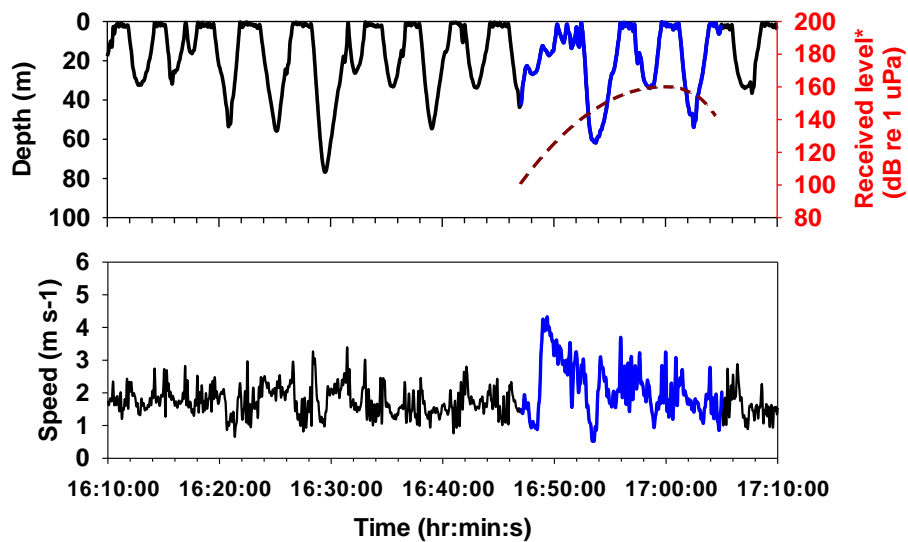
10 *Experimental design (BLS, JC, PLT), Visual observations and geospatial data (AD, CK, EF),*  
11 *Tagging operations (JAG, JC, ASF, EF, GS), Sound exposure operations (BLS, DM, CK), Tag*  
12 *data analysis (JAG, SD, MFM), Statistical analysis (ELH, SLD, JAG), Manuscript preparation*  
13 *(JAG, BLS, ELH), Manuscript revision (JAG, BLS, ASF, ELH, JC, PLT).*

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15 **Fine-scale movement for select CEE examples (Figure 1A, B).**

16 The data shown in Figure 1 is summarized to represent the nature of our broad scale analysis,  
17 where parameters were assessed on a dive-by-dive basis. Here we provide additional details on  
18 the fine-scale kinematics for two CEEs shown in Figure 1b and Figure 1c, including speed  
19 (Figure S1, S2) and body orientation relative to the sound source (Figure S3, S4, S5) as  
20 visualized in TrackPlot. An animation of the whale’s estimated trajectory during the CEE (Figure  
21 1B) is provided by the supplemental movie (bw10\_244c).

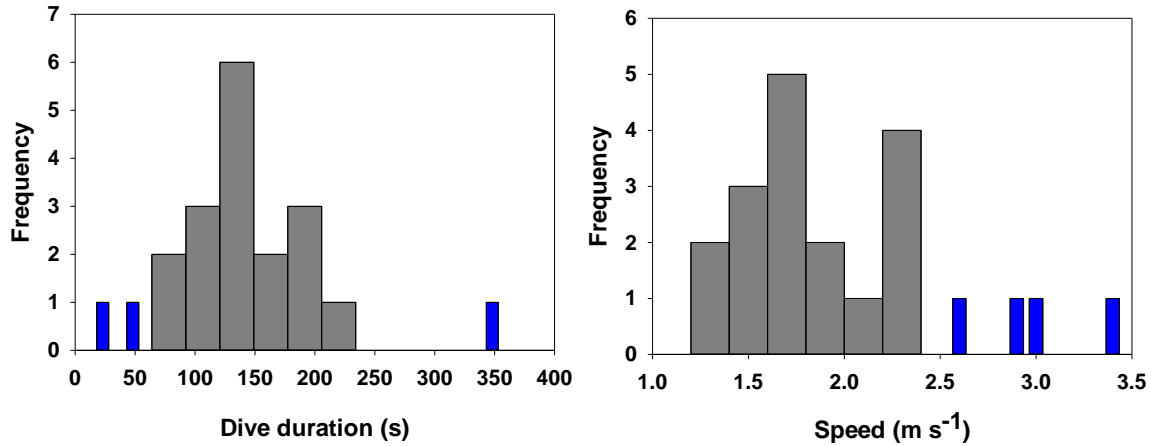
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23 The CEE in Figure S1 show data from a blue whale in a non-feeding behavioral state being  
24 exposed to mid-frequency simulated military sonar (MFA). The onset of sound exposure occurs  
25 during a mid-water dive where the whale was at a depth of approximately 30 m. The ascent  
26 phase following sound exposure was unusually prolonged and contained multiple undulations  
27 that do not normally occur during mid-water traveling dives (Figure S1 b,c). In addition, there  
28 was a marked increase in swimming speed ( $> 4 \text{ m s}^{-1}$ ) during the ascent phase of the initial  
29 exposure dive. We note that the acoustic record was clipped at this speed maximum ( $\sim 16:49$ ), so  
30 the speed estimated at that time is likely an underestimate and the whale's true speed could be as  
31 high as  $5 \text{ m s}^{-1}$ . Such speeds are consistent with field observations of flight speeds for blue  
32 whales when threatened by killer whales [1], although this blue whale exhibited a gradual  
33 decrease in speed for the remainder of the exposure period and therefore does not constitute a  
34 true flight response.



35  
36 **Figure S1.** Fine-scale movement for the CEE shown in Figure 1C. A blue whale in a non-  
37 feeding behavioral state was exposed to simulated mid-frequency military sonar. Dive profile

38 (black trace) and received sound levels (red circles and dashed line represent pings and the  
39 estimated received level via a quadratic spline).



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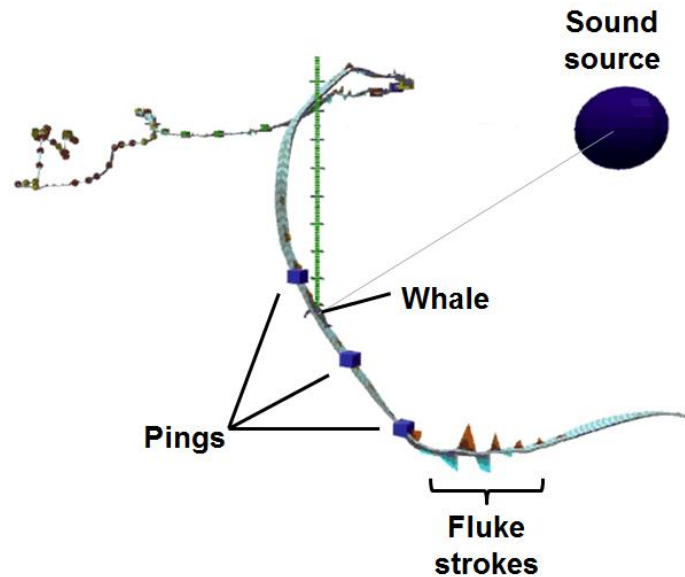
41 **Figure S2. Histograms for two primary response parameters before and during sound**  
42 **exposure for the CEE shown in Figure 1c. The mean values of each response parameter during**  
43 **all dives before exposure (gray) and the first four dives during exposure (blue).**

44

45 The CEE in Figures S3-S4 show data from a blue whale in a deep feeding mode (A) being  
46 exposed to pseudo-random noise (PRN). The onset of sound exposure occurs when the whale  
47 was at a depth of approximately 150 m (Figure S3B, S3B). During the ascent phase of the dive  
48 following sound exposure the whale appears to localize and orient towards the sound source  
49 (Figure S3C, S4C). The whale then turns away from the sound source during the first surface  
50 series (a sequence of breaths that follows a deep dive) following sound exposure (Figure S3D,  
51 S4D). The whale establishes a relatively steady heading over the next series of non-foraging  
52 dives and gradually increases speed (Figure S3E, S4E). The whale returns to a deep feeding  
53 behavioral state approximately 1 hour after the start of sound exposure. We have also provided

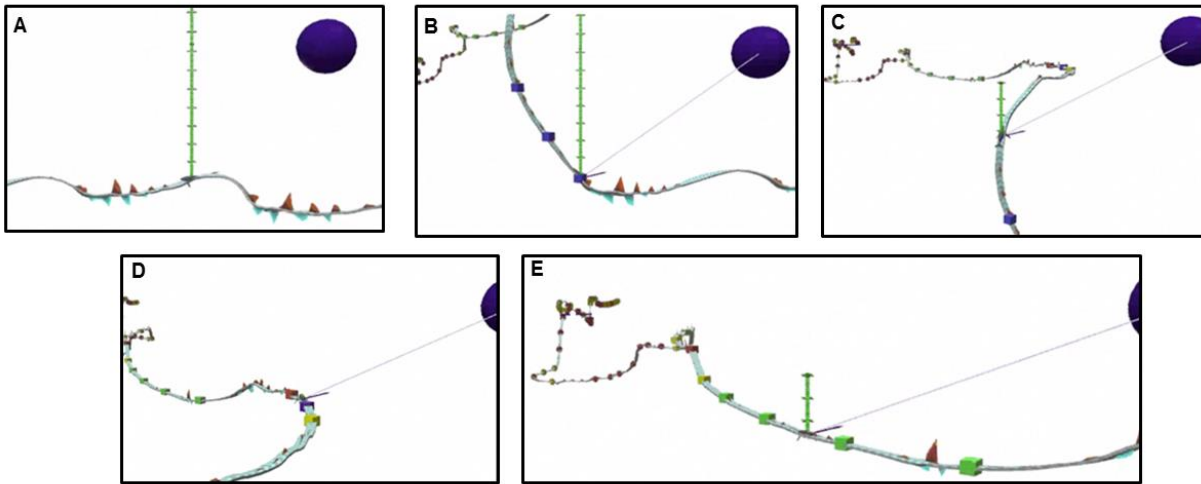
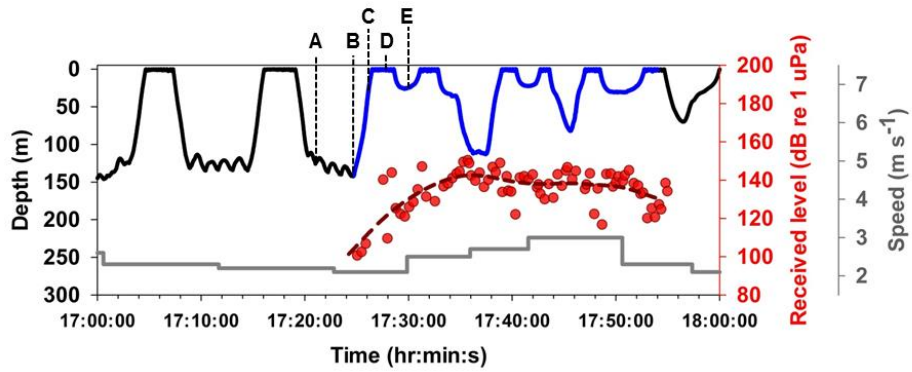
54 an animation “bw10\_244cObliqueWaudio” of the initial phase of this CEE. The symbols in the  
55 animation follow those in Figures S3-S4. Speed is 20x actual.

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58 **Figure S3. Explanation of TrackPlot symbols.** The estimated trajectory of the tagged whale is  
59 represented by a ribbon. The whale’s fluking strokes are represented by triangles that erupt  
60 above and below the ribbon to indicate upstrokes and down-strokes, respectively. The timing of  
61 each ping of sound, as detected by the hydrophone, is represented by a cube along the ribbon.  
62 The color of each cube reflects the magnitude of the received sound level, where hotter colors  
63 indicate higher received levels. The green line is orthogonal to the sea surface (large hatched  
64 marks denote 10 m depth intervals).



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66 **Figure S4. Oblique view of the tagged whale's behavior during the exposure experiment**

67 (**Figure 1B**). A blue whale in a deep feeding behavioral state was exposed to simulated pseudo-

68 random noise. (**A**) Undulations in the dive profile indicate lunge feeding at depth prior to sound

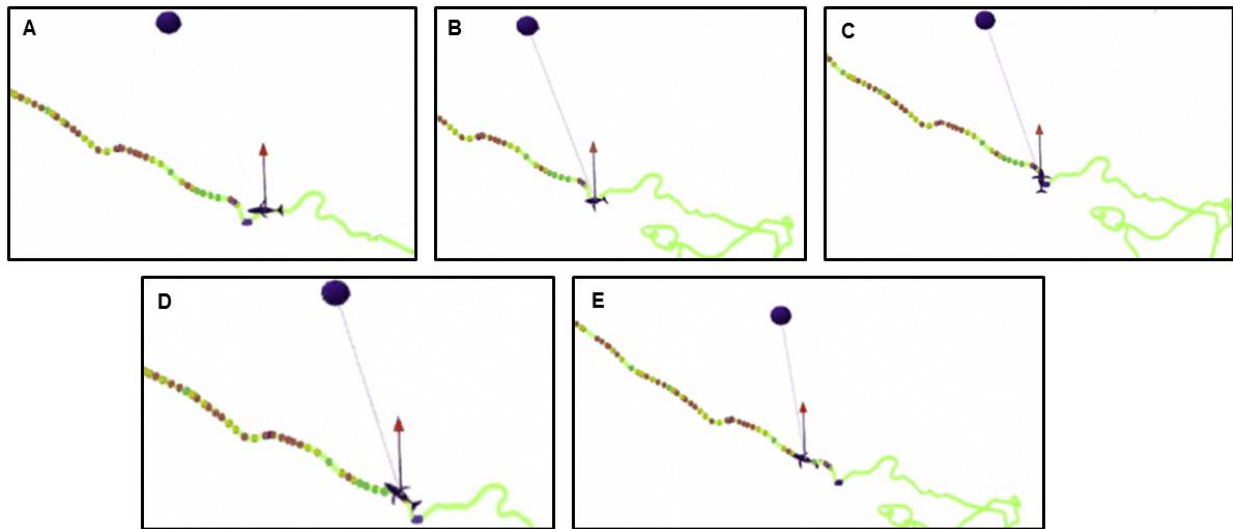
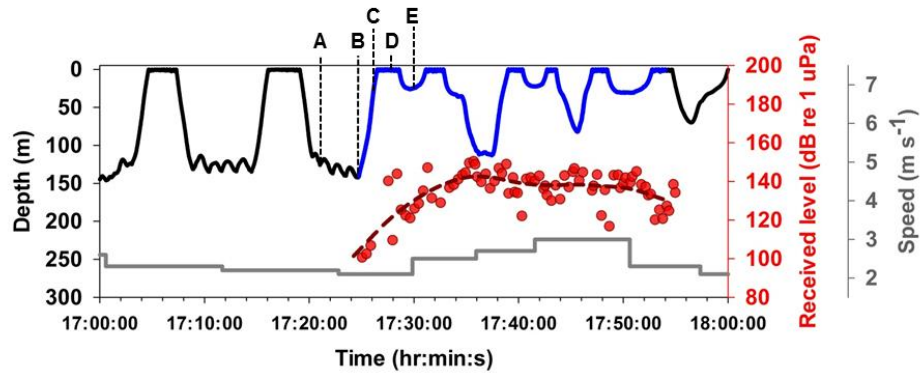
69 exposure. (**B**) Time of the first received ping. (**C**) Whale appears to localize and orient towards

70 the sound source. (**D**) The whale changes direction during the first surface series after sound

71 exposure. (**E**) The whale maintains roughly the same heading at the end of the first surface

72 series.

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75 *Figure S5. Aerial view of the tagged whale's behavior during the exposure experiment (Figure*  
 76 *1B). Frames (A-E) represent the same stages of the CEE as shown in Figure S4.*

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79 **Consumption loss estimate for behavioral response shown in figure 1B (also figure S4-5).**

80 Rorqual whales (Balaenopteridae) are obligate lunge feeders that engulf dense aggregations of  
 81 prey in discrete mouthfuls [2]. The amount of prey-laden water that a rorqual processes in a  
 82 single foraging dive is the product of lunge frequency [3] and engulfment capacity [4] and this  
 83 parameter can be generated over an entire foraging bout [5, 6]. We invoked this methodology to  
 84 determine the changes in feeding rate over the course of the CEE for the tagged blue whale

85 shown in figure 1b (stimuli: PRN). Before the CEE, the blue whale was continuously foraging at  
86 a rate of 4.2 lunges per dive. For an average krill density of  $0.5 \text{ kg m}^{-3}$  and a mean blue whale  
87 engulfment capacity of  $110 \text{ m}^3$  [7], the tagged blue whale acquired 1,375 krill in 72 min prior to  
88 the onset of sound exposure, thus yielding an overall feeding rate of 19 kg of krill per minute.  
89 The tagged blue whale stopped feeding at the onset of sound exposure for a total of 62 minutes,  
90 suggesting that this behavioral response in the form cessation of feeding resulted in an energetic  
91 loss of 1,200 krill. The magnitude of this consumption loss is approximately commensurate with  
92 a blue whale's daily energetic demand [7]. Therefore, this example suggests that exposure of  
93 mid-frequency anthropogenic sound could have major effects on blue whale foraging ecology.

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## 96 **Detailed results from statistical analyses**

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### 98 Paired PCA-GAMM Results

99 Our paired PCA-GAMM analyses revealed significant differences related to sound exposure.

100 The primary eigenvector of all three parameter groupings had a significant effect with respect to  
101 sound exposure (Dive metrics,  $p=0.045$ ;  $r^2 \text{ adj} = 0.16$ ; orientation metrics,  $p = 0.019$ ;  $r^2 \text{ adj} =$   
102  $0.03$ ; horizontal metrics,  $p<0.005$ ;  $r^2 \text{ adj} = 0.07$ ), with dive metrics specifically showing a three-  
103 way interaction effect among treatment status, treatment dive (descent, ascent, or bottom phase),  
104 and behavioral state. Although responses clearly varied among individuals (Figure 1), some of  
105 the variability was explained by behavioral state and sound type (Figure 2, Table S1).

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<b>Dive Axis 1 – Before/During/After model (<math>r^2</math> adj.=0.14, n=430)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	1.11522	0.908	0.3646
Treatment.status	0.14671	1.561	0.1193
<b>Treatment.dive</b>	<b>0.01645</b>	<b>0.110</b>	<b>0.9125</b>
Bstate.PB	-1.11144	-1.769	0.0776
<b>Treatment.status:Treatment.dive:Bstate.PB</b>	<b>0.20095</b>	<b>2.088</b>	<b>0.0374</b>
	<b>Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	4.343e-08	0.071	0.790
s(MinRL)	1.427e-08	0.000	0.996
s(AvgRL)	2.831e-08	0.025	0.875
<b>s(X.Pings)</b>	<b>9.629e-01</b>	<b>18.444</b>	<b>2.17e-05</b>

<b>Dive Axis 1 - During model (<math>r^2=0.38</math>, n=88)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	2.8532	1.35	0.1806
Treatment.dive	-0.2779	-1.079	0.2836
Treatment.type	-1.0218	-0.779	0.4379
<b>Bstate.PB</b>	<b>-1.6198</b>	<b>-2.032</b>	<b>0.0454</b>
<b>Treatment.dive:Treatment.type:Bstate.PB</b>	<b>0.2217</b>	<b>2.172</b>	<b>0.0327</b>
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
<b>s(MaxRL)</b>	<b>2.1683</b>	<b>9.583</b>	<b>0.000129</b>
<b>s(MinRL)</b>	<b>0.81</b>	<b>4.501</b>	<b>0.036852</b>
s(AvgRL)	0.8032	3.499	0.064916
<b>S(X.Pings)</b>	<b>2.1683</b>	<b>9.583</b>	<b>0.000129</b>

<b>Orientation Axis 1 - Before/During/After model (<math>r^2= 0.04</math>, n=430)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	0.8153	0.51	0.6104
<b>Treatment.status</b>	<b>-0.20616</b>	<b>-2.354</b>	<b>0.0191</b>
Treatment.dive	-0.14956	-1.073	0.2838
Bstate.PB	-0.02277	-0.03	0.9763
Boats.cat	-0.97714	-0.58	0.5624
Treatment.status:Treatment.dive:Bstate.PB	-0.04193	-0.474	0.6355
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>



s(MaxRL)	3.93E-08	0.188	0.6648
s(MinRL)	1.35E-08	0.107	0.7434
s(AvgRL)	3.54E-08	0.167	0.683
<b>S(X.Pings)</b>	<b>8.38E-01</b>	<b>6.534</b>	<b>0.0109</b>

<b>Orientation Axis 1 - During model (r<sup>2</sup>=-0.01, n=84)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	1.1724	0.441	0.661
Treatment.dive	0.1824	0.363	0.718
Treatment.type	1.132	0.966	0.337
Bstate.PB	-0.0718	-0.056	0.955
Boats.cat	-3.3751	-1.309	0.194
Treatment.dive:Treatment.type:Bstate.PB	-0.2612	-1.168	0.246
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	1.27E-09	0.013	0.909
s(MinRL)	1.24E-09	0.036	0.85
s(AvgRL)	3.97E-09	0.017	0.896

<b>Orientation Axis 2 - Before/During/After model (r<sup>2</sup>=0, n=430)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	0.61669	0.786	0.432
Treatment.dive	-0.10039	-1.111	0.267
Treatment.status	-0.02914	-0.512	0.609
Bstate.PB	-0.29209	-0.779	0.436
Boats.cat	-0.26123	-0.316	0.752
Treatment.dive:Treatment.status:Bstate.PB	0.02268	0.444	0.657
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	1.43E-08	0.259	0.611
s(MinRL)	5.81E-09	0.049	0.825
s(AvgRL)	1.74E-08	0.232	0.63

<b>Orientation Axis 2 - During model (r<sup>2</sup>=0.06, n=87)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	0.509635	0.561	0.576

Treatment.dive	0.008127	0.031	0.976
Treatment.type	-0.97422	-1.537	0.128
Bstate.PB	-0.28422	-0.643	0.522
Boats.cat	0.266359	0.277	0.783
Treatment.dive:Treatment.type:Bstate.PB	0.082943	0.79	0.432
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	8.50E-10	0.003	0.96
s(MinRL)	6.97E-10	0.061	0.805
s(AvgRL)	1.44E-09	0.001	0.981

<b>Horizontal Metrics Axis 1 - Before/During/After model (<math>r^2=0.07</math>, <math>n=418</math>)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	-0.83852	-0.671	0.503
<b>Treatment.status</b>	<b>0.45282</b>	<b>7.427</b>	<b>6.46E-13</b>
Treatment.dive	-0.01493	-0.156	0.876
Bstate.PB	0.29095	0.486	0.627
Boats.cat	-0.07037	-0.053	0.957
Treatment.status:Treatment.dive:Bstate.PB	-0.00307	-0.057	0.955
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	8.24E-09	0.506	0.477
s(MinRL)	1.37E-08	0.473	0.492
s(AvgRL)	2.07E-08	0.494	0.483
s(X.Pings)	1.15E-10	0.154	0.695

<b>Horizontal Metrics Axis 1 - During (<math>r^2=0.01</math>, <math>n=87</math>)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	-0.16179	-0.069	0.945
Treatment.dive	0.20745	0.444	0.658
Treatment.type	0.05452	0.042	0.967
Bstate.PB	0.53587	0.474	0.637
Boats.cat	-1.29406	-0.57	0.57
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	4.14E-09	0.014	0.905

<b>Horizontal Metrics Axis 2 - Before/During/After model (<math>r^2=0.14</math>, <math>n=418</math>)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	-1.02561	-1.537	0.1251
Treatment.status	-0.02018	-0.307	0.7587
Treatment.dive	-0.03087	-0.299	0.7651
Bstate.PB	0.55505	1.745	0.0818
<b>Boats.cat</b>	<b>1.49556</b>	<b>2.138</b>	<b>0.0331</b>
Treatment.status:Treatment.dive:Bstate.PB	-0.01152	-0.197	0.8439
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	8.22E-09	0.088	0.766
s(MinRL)	9.80E-09	0.414	0.52
s(AvgRL)	2.32E-08	0.208	0.648
s(X.Pings)	9.63E-09	2.05	0.153

<b>Horizontal Metrics Axis 2 - During (<math>r^2=0.31</math>, <math>n=87</math>)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	-1.9134	-2.432	0.01721
Treatment.dive	-0.1201	-0.401	0.68941
Treatment.type	0.2938	0.353	0.72522
<b>Bstate.PB</b>	<b>0.8393</b>	<b>2.212</b>	<b>0.02977</b>
<b>Boats.cat</b>	<b>2.6607</b>	<b>3.206</b>	<b>0.00192</b>
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	1.86E-09	0.323	0.572

<b>Horizontal Metrics Axis 3 – Before/During/After model (<math>r^2=0.09</math>, <math>n=418</math>)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	-0.76605	-0.959	0.338
Treatment.status	0.06668	1.342	0.18
Treatment.dive	-0.04646	-0.597	0.551
Bstate.PB	0.35273	0.923	0.357
Boats.cat	-0.20514	-0.244	0.807
Treatment.status:Treatment.dive:Bstate.PB	0.03869	0.876	0.381
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	1.78E-08	0.388	0.534

s(MinRL)	9.83E-09	0.01	0.922
s(AvgRL)	1.51E-08	0.284	0.595
s(X.Pings)	2.28E-07	2.694	0.101

<b>Horizontal Metrics Axis 3 - During (<math>r^2=0.15</math>, <math>n=87</math>)</b>	<b>Estimate</b>	<b>t statistic</b>	<b>p-value</b>
(Intercept)	-0.644	-0.535	0.594
Treatment.dive	0.2534	0.814	0.418
Treatment.type	-1.1845	-1.36	0.177
Bstate.PB	0.4554	0.781	0.437
Boats.cat	0.0453	0.038	0.97
	<b>Est Deg Free</b>	<b>F statistic</b>	<b>p-value</b>
s(MaxRL)	4.37E-09	0.042	0.839

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**Table S1. Paired PCA-GAMM Results.**

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